How empty is empty? Defining environment, from voids to field to clusters

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Environment, why we care ...

- we can finally do it well
- who wants to be just "average"
- different environment, different physics



- I. How we define environment and voids
- 2. Physical vs. statistical measures of environment
- 3. Some of my own results
- 4. An environment project







"Group" finders:

- Close pairs, friends of friends, ...
- Optimal linking length?
- Won't find voids, but will identify isolated galaxies

N'th nearest neighbour:

- What "n" is optimal?
- How to compare dense with sparse populations?

Fixed aperture:

- What kind of aperture (top-hat, Gaussian, ...)?
- Smoothed on what scale?
- Loss of information on smaller scales (e.g. halo radii typically <2Mpc)

Using the underlying structure itself:

- Halo mass (i.e. bound structures)
- The dark matter density field
- Observation vs. theory
- Dealing with bias

Issues:

- 2D vs. 3D.
- Dealing with selection, incompleteness and volume effects
- Comparing different environment measures

Defining voids

Use the "void finder" algorithm

Defining voids

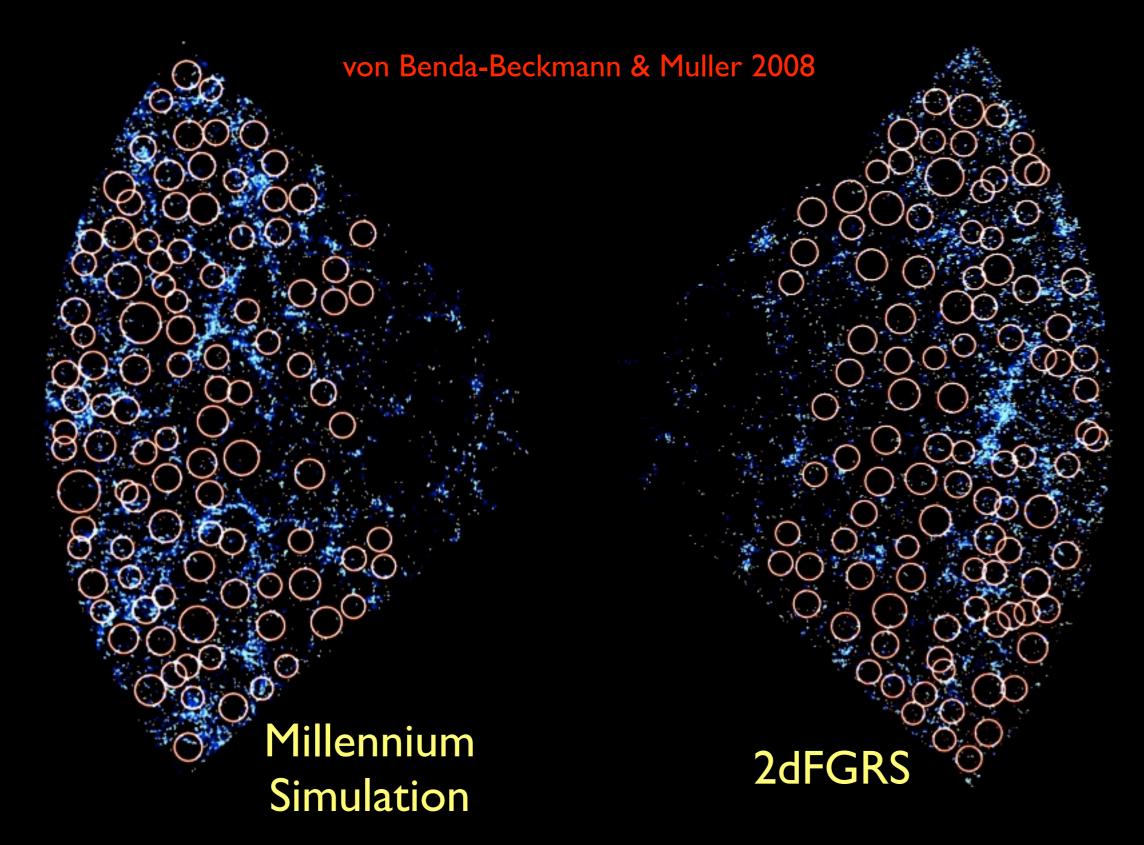
- "void" galaxies vs. "wall" galaxies (e.g. Hoyle et al. 2005)
- Maximal non-overlapping spheres (e.g. Patiri et al. 2006)
- Grid based (e.g. Colberg et al. 2005)
- Something more clever (talk to Rien)

Defining voids

Issues:

- Selection, incompleteness and volume effects
- How empty do you have to be to be a void $(\delta < -0.6, \delta < -0.9)$?
- Comparing different void measures

Do they work?



Statistical measures of environment

- 2-pt clustering amplitude links to both environment and halo mass
- Shape statistics voids, filaments, sheets, clusters
- voids can be just as clustered as clusters

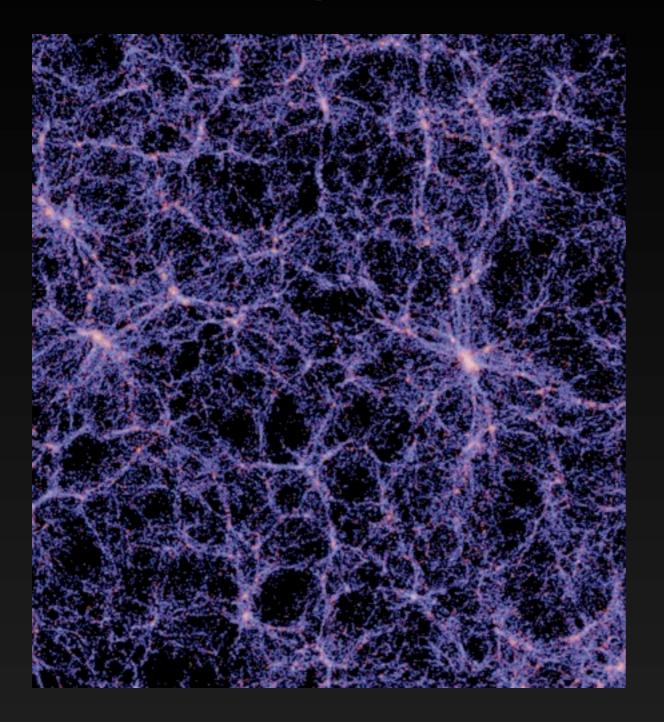
Environment dependent quenching?

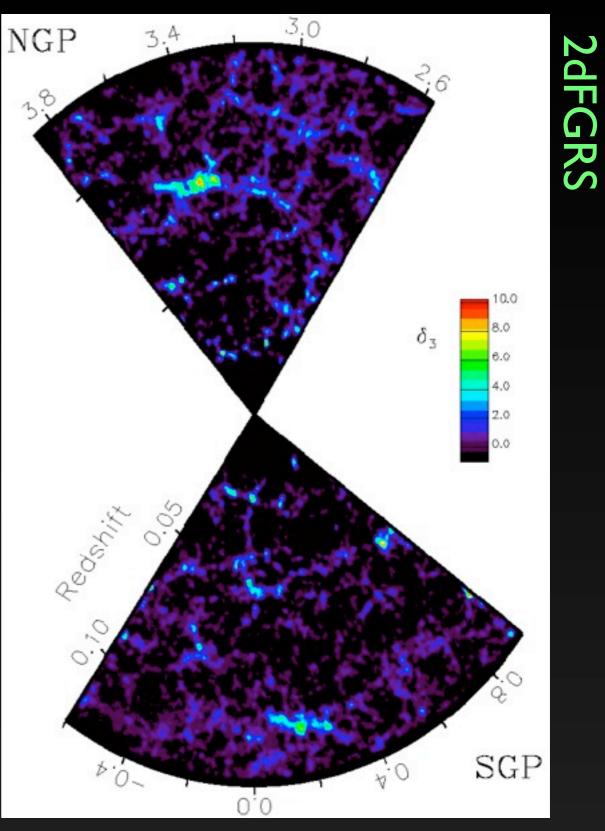
When I say "environment" this is what I mean ...

Local (number) density is determined in top-hat spheres of radius 8h⁻¹Mpc:

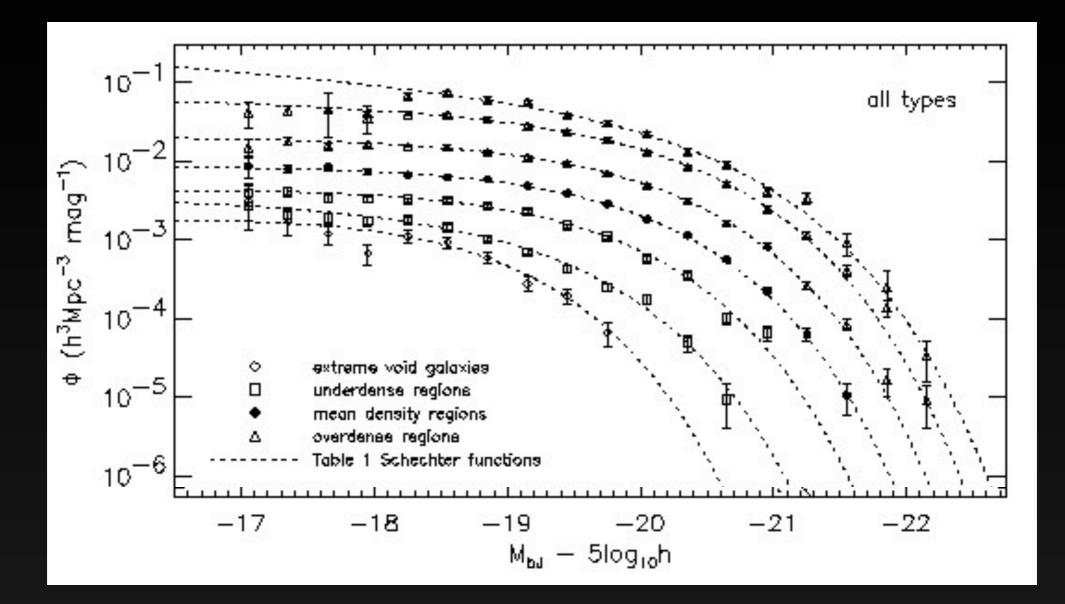
$$\delta_{8} = \delta \rho_{g} / \langle \rho_{g} \rangle$$

Millennium Simulation semi-analytic model



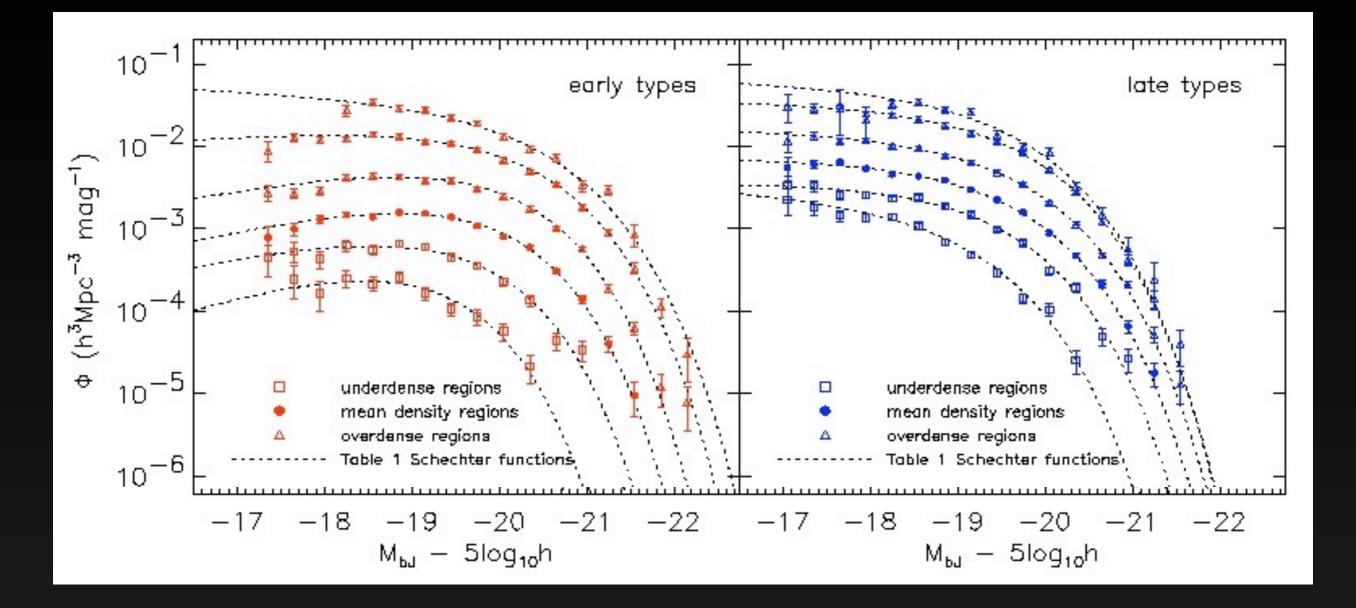


2dFGRS luminosity function



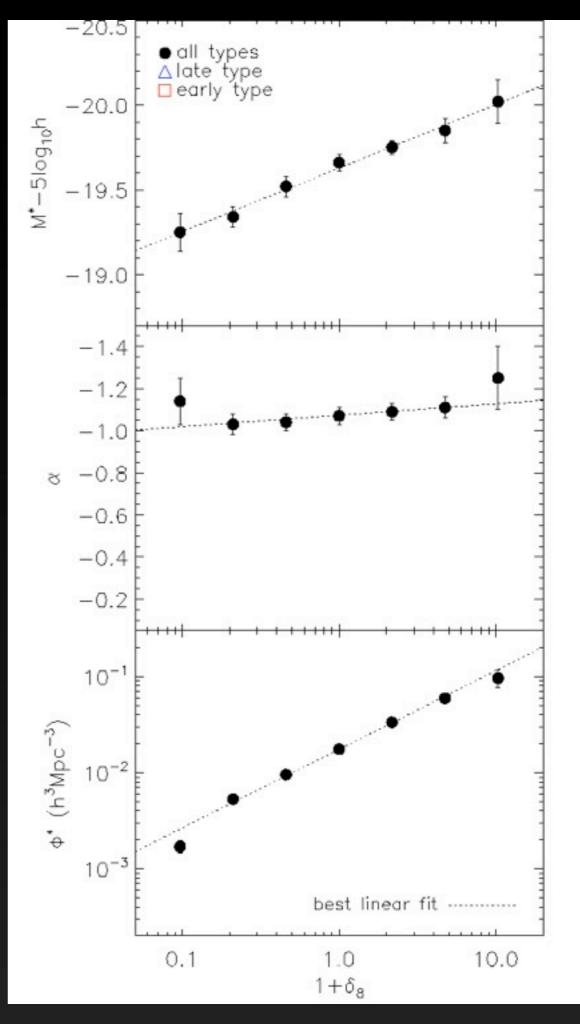
Extreme void: $-1.0 < \delta_8 < -0.9$ Void: $-1.0 < \delta_8 < -0.75$ Mean: $-0.43 < \delta_8 < 0.32$ Cluster: $\delta_8 > 6.0$

2dFGRS luminosity function

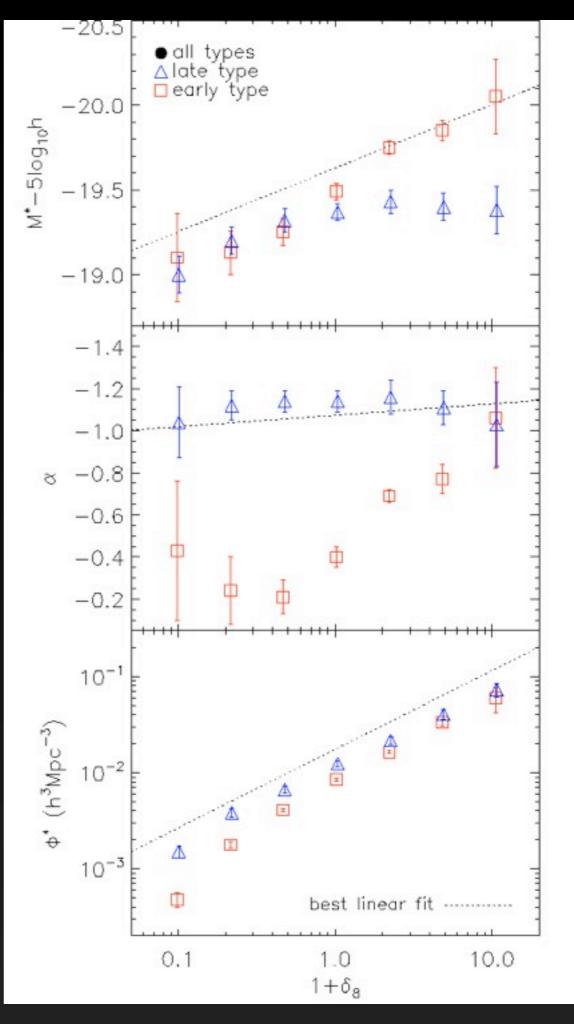


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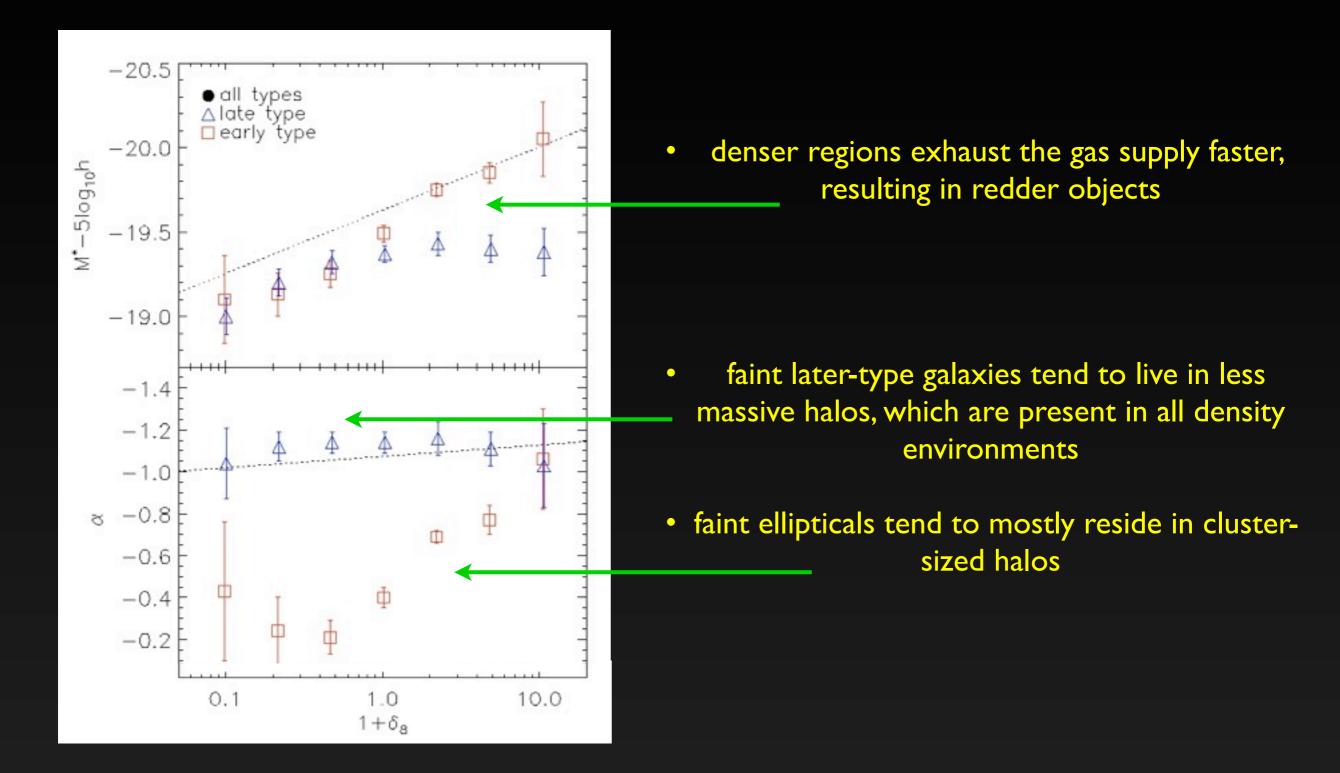
2dFGRS Schechter parameters vs. environment



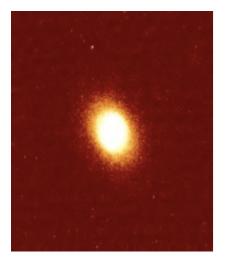
2dFGRS Schechter parameters vs. environment

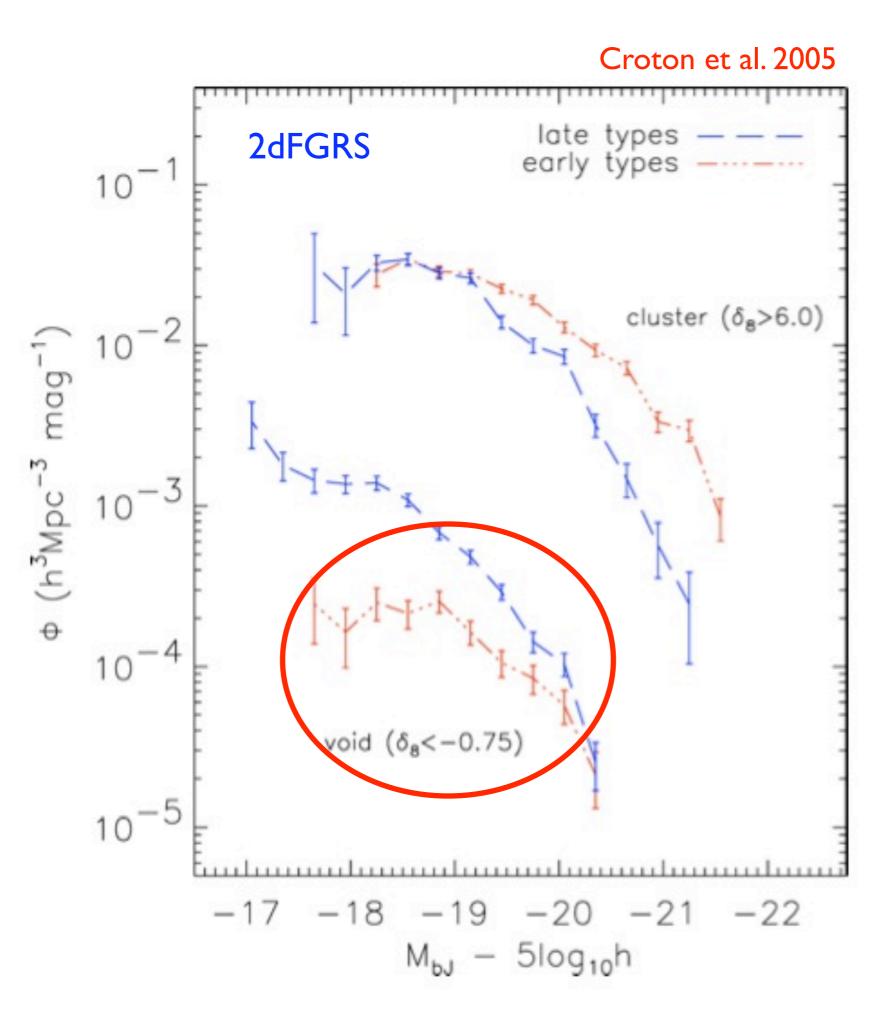


HOD model interpretation

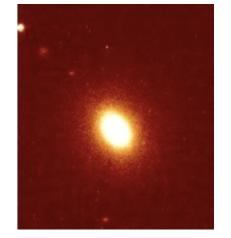


The environment dependence of galaxy properties can be accounted for by the dependence of halo mass on environment



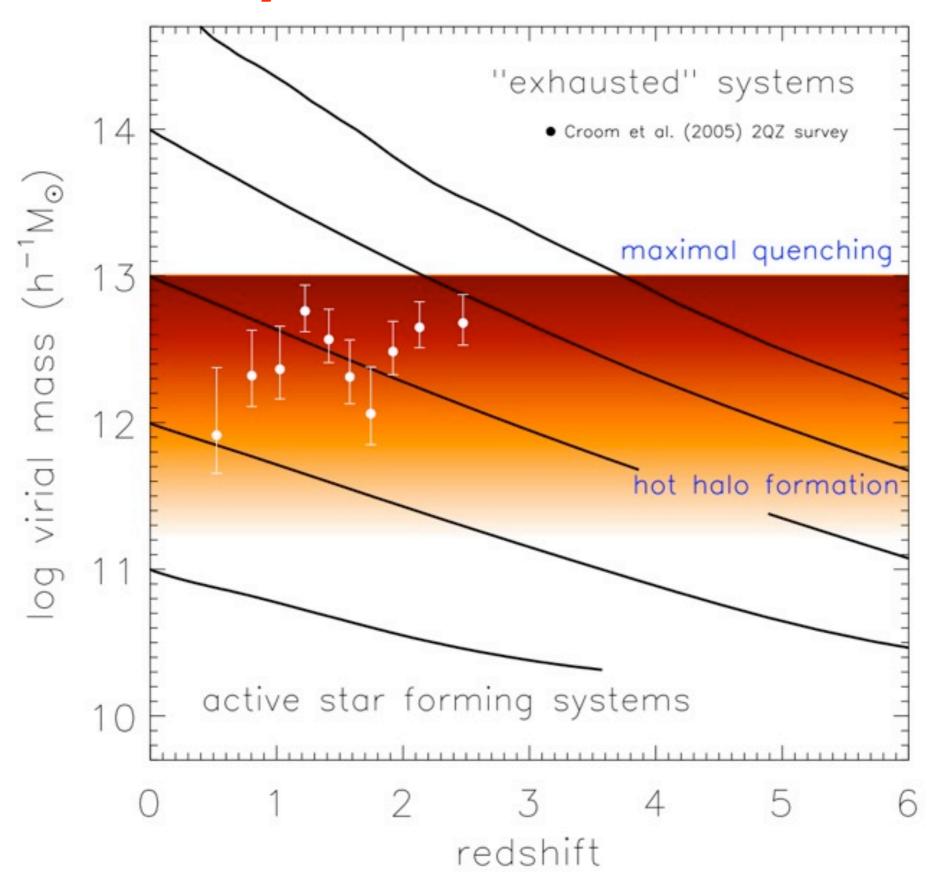






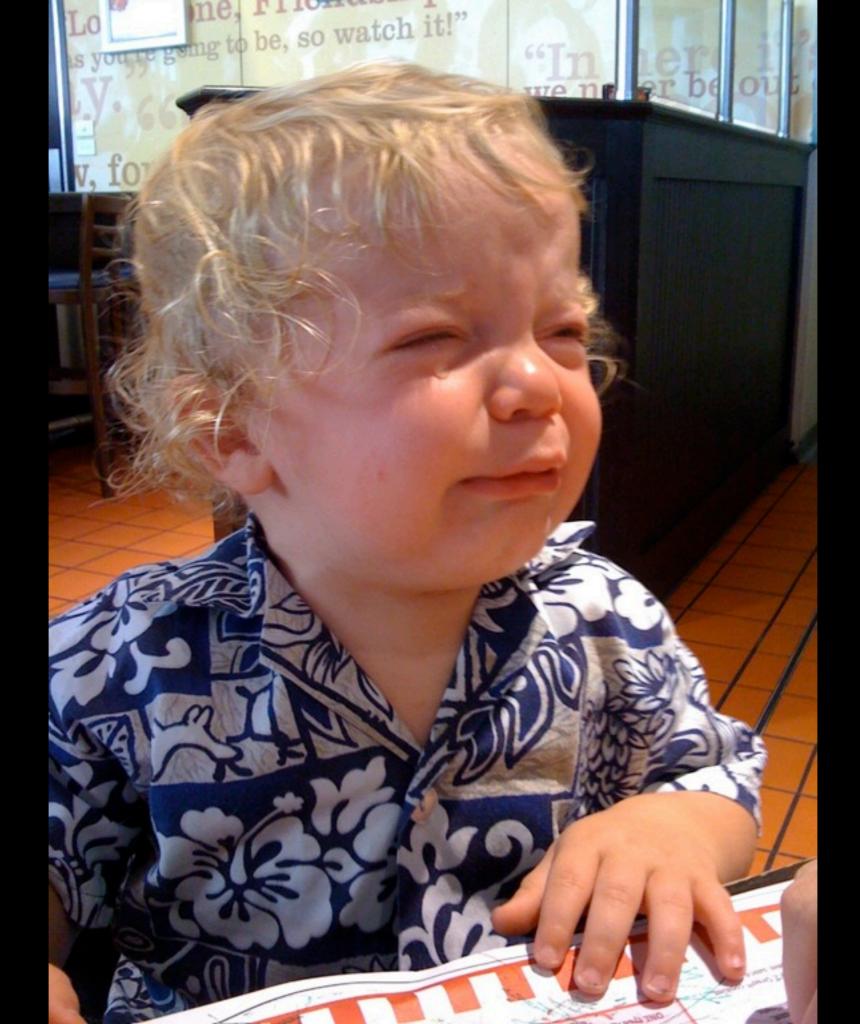


Galaxy formation models

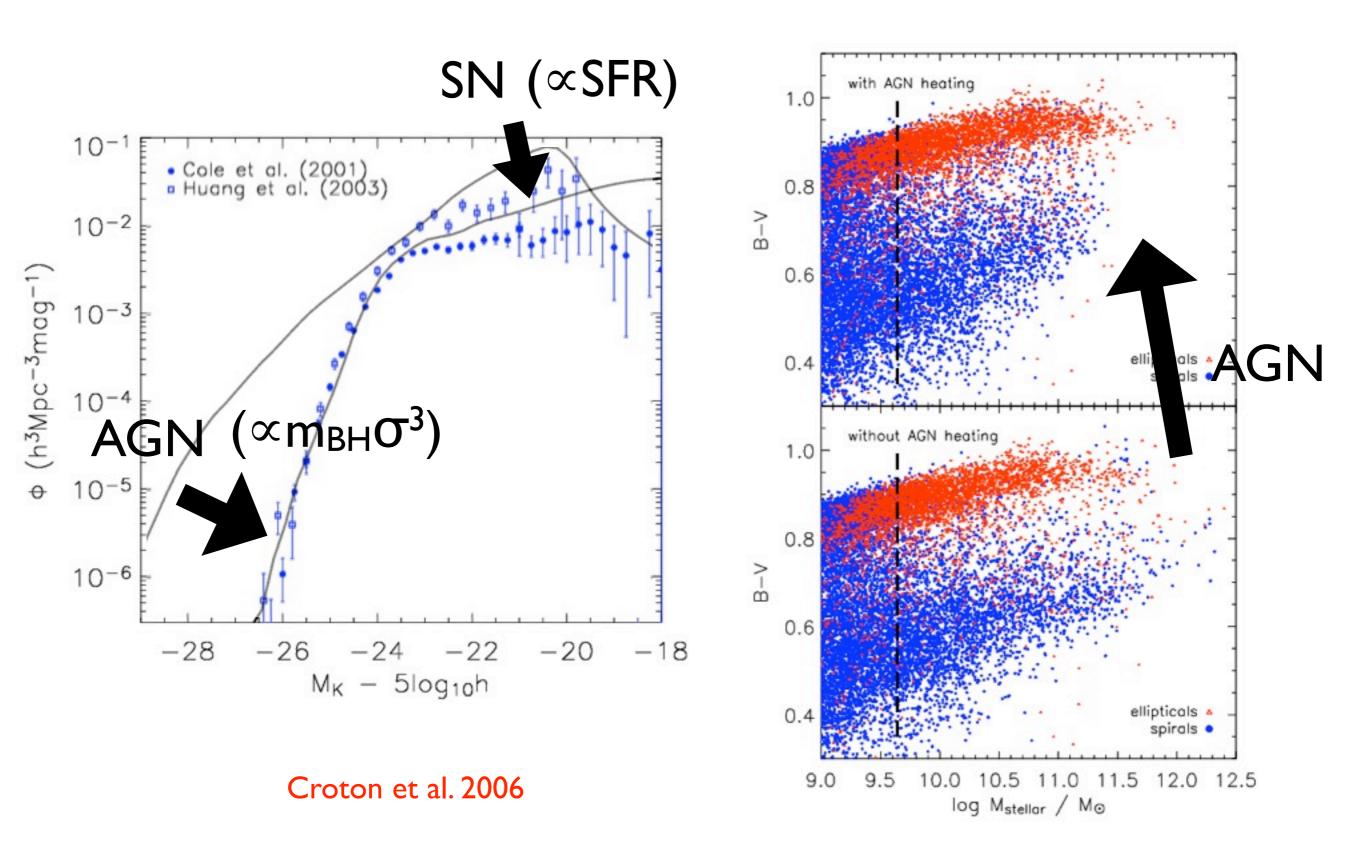


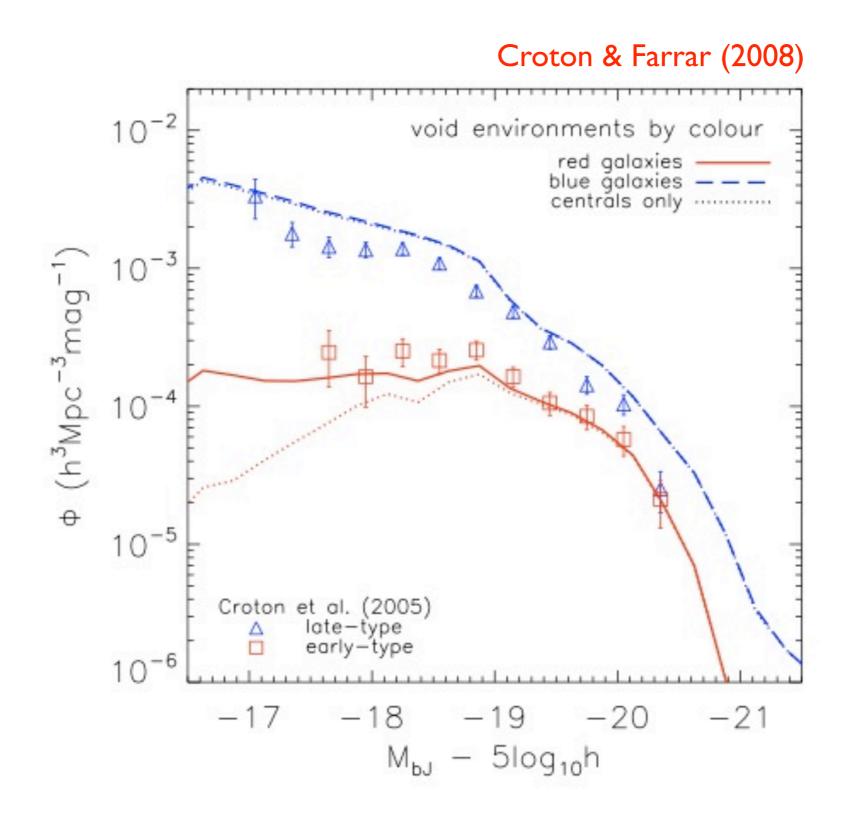






Galaxy formation models

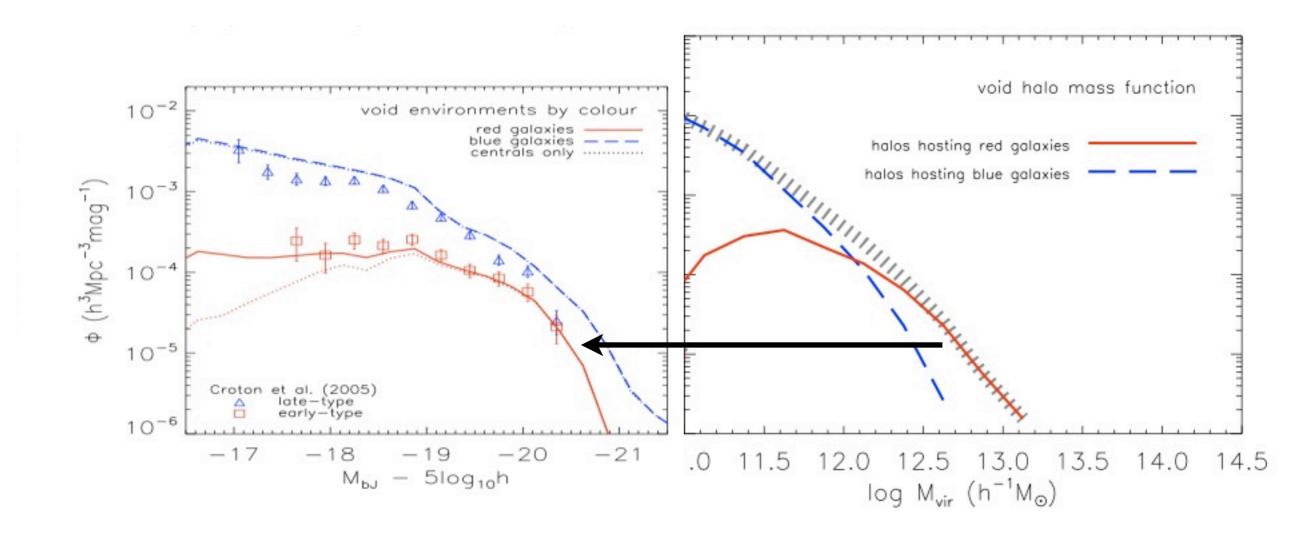




The Millennium Simulation semi-analytic galaxy formation model

So what's special about earlytype void galaxies?

Croton & Farrar (2008)



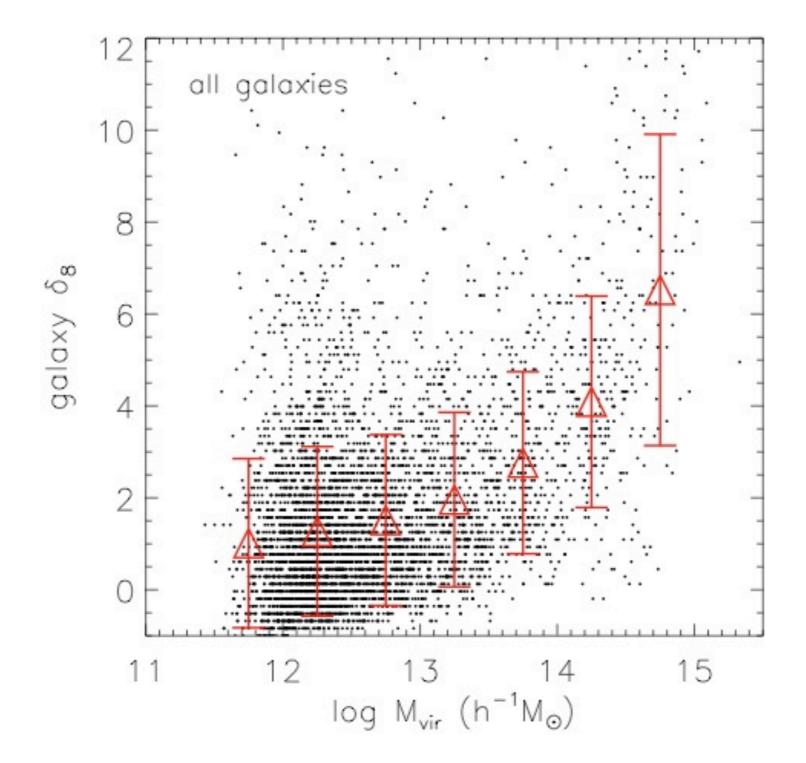
Halo mass function in different environments

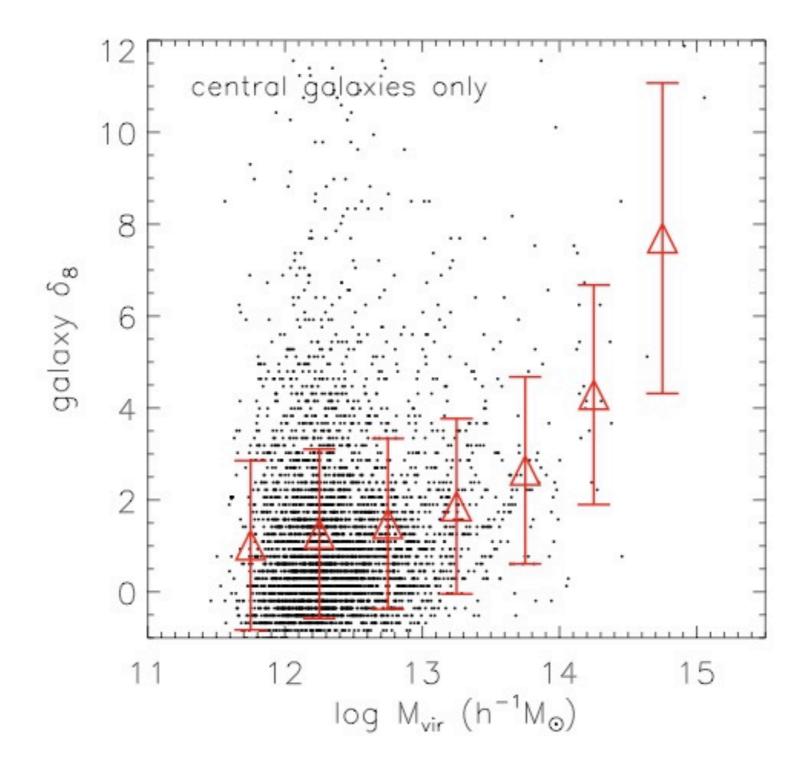
The red/blue void galaxy abundance can be accounted for by the dependence of halo mass on environment

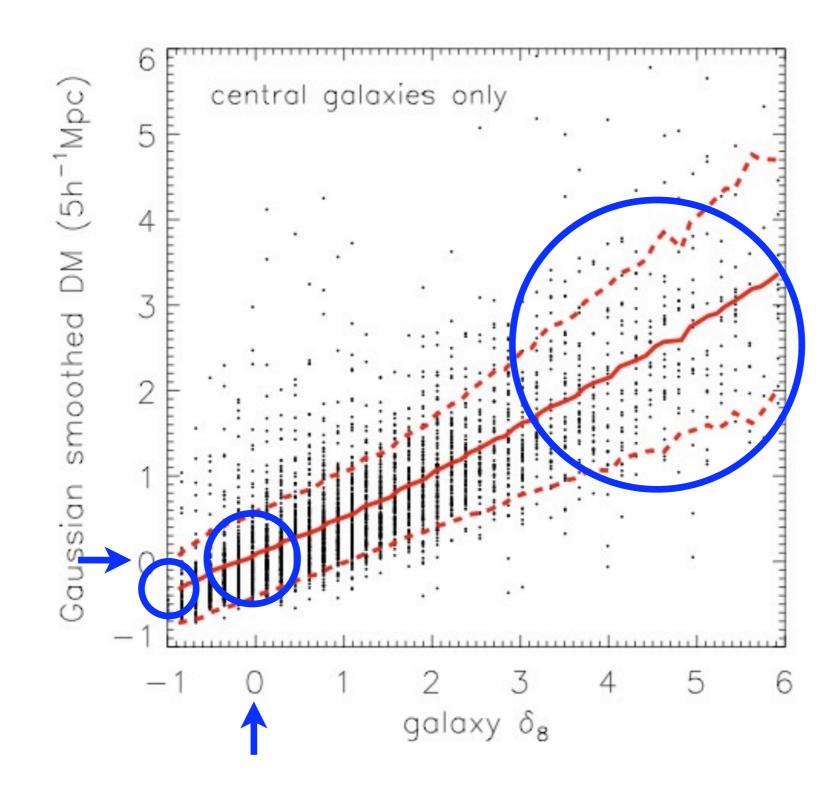
Apply multiple environment/isolated/void measures to a common mock catalogue:

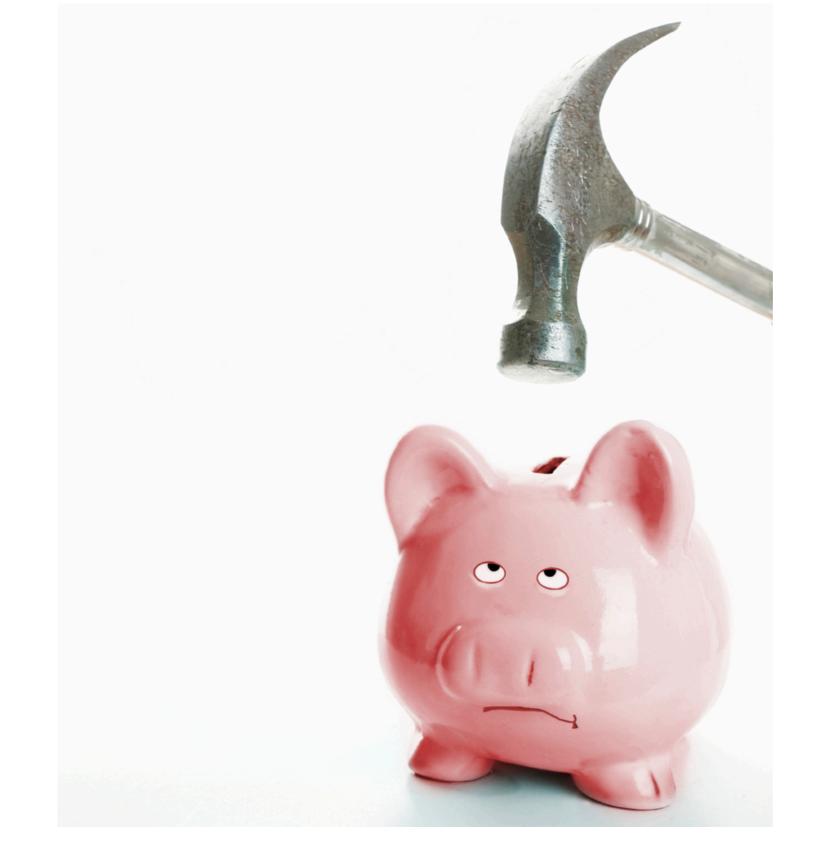
- How do different measures of environment compare?
- How are our end results coloured by the environment measures we use?

- fixed aperture (spherical, cylinder) on small and large scales
- N'th nearest neighbour
- group finders and isolation criterion
- halo mass and the underlying DM density field
- 2D vs 3D measures
- others?









Please join us!